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### Posterior Computation for Hierarchical Dirichlet Process Mixture Models: Application to Genetic Association Studies of Quantitative Traits in the the Presence of Population Stratification

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# Introduction

In ?, we introduced a unified hierarchical Bayesian semiparametric model for genetic association studies of quantitative traits in the presence of population stratification. The model uses a Dirichlet Process Mixture (DPM) construction to account for stratification in making association inference. It also involves a nonparametric sparsity prior to accommodate the expectation that most genetic markers are unrelated to the phenotype in a large association screen. In this technical report, we describe the necessary computational details for implementing the DPM model (C code available from http://www.biostat.mcw.edu/software/SoftMenu.html). We begin with a short description of the DPM model, and then discuss its implementation through Markov chain Monte Carlo (MCMC) sampling.

Consider a continuous phenotype  $Y_i$  observed on a sample of N unrelated individuals. Suppose each individual is then genotyped at L Single Nucleotide Polymorphism (SNP) markers. The extension to more polymorphic markers is straightforward, although the available C code does not currently implement such a case. Define  $V_{li} = 1$  (0 otherwise) if the  $i^{th}$  individual is homozygous for the reference (or minor) allele at the  $l^{th}$  SNP, and  $W_{li} = 1$  (0 otherwise) if the individual is heterozygous at that SNP. Then let  $\beta_{l1}$  and  $\beta_{l2}$  represent the regression effects for individuals heterozygous and homozygous respectively at the  $l^{th}$  SNP. Finally, let  $X_{li} = [W_{li} \ V_{li}]$  and  $\beta_l = [\beta_{l1}, \beta_{l2}]$ . The hierarchical DPM model can then be

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defined as follows.

 $\alpha_G \sim$ 

$$\begin{split} L\left(Y_{i}|\mu_{i},\tau_{\epsilon}\right) &= \frac{\tau_{\epsilon}^{1/2}}{\sqrt{2\pi}} \exp\left[\frac{-\tau_{\epsilon}}{2}\left(Y_{i}-\mu_{i}\right)^{2}\right] \\ \mu_{i} &= \beta_{0i} + \sum_{l=1}^{L} X_{li}\beta_{l} \\ L\left(W_{li},V_{li}|\theta_{li}\right) &= \frac{2^{W_{li}}e^{\theta_{li}(2V_{li}+W_{li})}}{\left(1+e^{\theta_{li}}\right)^{2}} \quad i=1,..,N \quad l=1,..,L \\ \beta_{0i},\theta_{1i},...,\theta_{Li}|G &\stackrel{i.i.d}{\sim} \quad G \quad i=1,..,N \\ G|\alpha_{G},G_{0} &\sim \quad \text{DP} \quad (\alpha_{G},G_{o}) \\ G_{0} &= N \quad (\beta_{0};\mu_{0},\tau_{0})\prod_{l=1}^{L} N \quad (\theta_{l};\mu_{\theta},\tau_{\theta}) \\ \beta_{l}|H &\stackrel{i.i.d}{\sim} \quad H \quad l=1,..,L \\ H|\alpha_{H},H_{0} &\sim \quad \text{DP} \quad (\alpha_{H},H_{0}) \\ H_{0} &= \pi\delta_{(0,0)}(\cdot) + (1-\pi)MVN_{2} \quad (M_{\beta},T_{\beta}) \\ \pi &\sim \quad \text{Beta} \quad (c_{1},d_{1}) \\ \tau_{\epsilon} &\sim \quad \text{Gamma} \quad (\eta_{2},\lambda_{2}) \quad \text{and} \quad \alpha_{H} \sim \quad \text{Gamma} \quad (\eta_{3},\lambda_{3}) \end{split}$$

Note: Throughout the document, we use the following parametrization of gamma density,  $X \sim \text{Gamma}(\alpha, \lambda)$ ,

$$f(x) \propto x^{\alpha-1}e^{-\lambda x}$$

In the above formulation,  $\theta_{li} = \text{logit } (\pi_{li})$  where  $\pi_{li}$  presents the reference allele frequency for the  $i^{th}$  individual at the  $l^{th}$  SNP.  $\delta_{(0,0)}(\cdot)$  represents a Dirac delta function indicating a point mass at (0,0). In addition,  $N(x;\mu,\tau)$  denotes a normal density with mean  $\mu$  and precision  $\tau$  and  $MVN_p(x; M, T)$  represents a p-dimensional multivariate normal with mean vector M and precision matrix T. For each of the Dirichlet Processes, we have assumed gamma priors for the scalar mass parameters  $\alpha_G$  and  $\alpha_H$  following ?; alternatively they could be taken as to be fixed constants. Figure 1 displays the model as a directed acyclic graph (DAG).



Figure 1: DAG for Hierarchical DPM Model of Quantitative Traits

## **Posterior Computations**

We now describe in full detail the necessary steps to implement posterior inference using MCMC sampling. Given an initial state  $\Theta_0 = \left[\theta_i^{(0)} \text{ for all } i, \beta_l^{(0)} \text{ for all } l, \tau_{\epsilon}^{(0)}, \alpha_G^{(0)}, \alpha_H^{(0)}\right]$ , iterate through the following steps.

### **STEP 1:** Update for $\theta_i$

In order to update  $\theta_i = [\beta_{0i}, \theta_{1i}, ..., \theta_{Li}]$  we employed a Metropolis-Hastings based algorithm described in ? (algorithm 5). The algorithm of Neal utilizes the notion of a configuration in updating each  $\theta_i$ . At a given MCMC iteration, the  $\theta_i$  will have clustered to a set of  $K_{\theta} < N$ distinct values denoted as  $\theta^* = [\theta_1^*, ..., \theta_{K_{\theta}}^*]$ . Note that each element of  $\theta^*$  represents an L+1dimensional vector containing the regression parameter  $\beta_0$  and the logit of allele frequencies at each SNP. We then define the configuration indicators  $s_i$  where  $s_i = j$  if and only if  $\theta_i = \theta_i^*$ . Finally let  $n_j$  represent the number of  $s_i$  currently equal to j. **Step 1a:** Perform the following proposal step for R iterations. For i = 1, 2, ..., N; propose a new distinct atom membership  $(s_i^*)$  for the  $i^{th}$  observation. The approach of ? uses the conditional prior as a proposal distribution for  $s_i^*$ . Let  $s_{(-i)}$  denote the set of all configuration indicators minus  $s_i$ , and let  $n_j^{(-i)}$  denote the number of  $s_c = j$  for c = 1, 2, ..., i - 1, i + 1, ..., N.

$$P\left(s_{i}^{*}=j|s_{(-i)}\right) = \frac{n_{j}^{(-i)}}{\alpha_{G}+N-1} \text{ for } j=1,2,..,K_{\theta} \text{ and}$$
$$P\left(s_{i}^{*}=K_{\theta}+1|s_{(-i)}\right) = \frac{\alpha_{G}}{\alpha_{G}+N-1}$$

Note that if  $s_i^* = K_{\theta} + 1$  is proposed then a new value  $\theta_{K_{\theta}+1}$  needs to be sampled from  $G_0$ . Accept the move to  $s_i^*$  with the following probability.

$$P(s_i, s_i^*) = \min[1, R] \text{ where}$$

$$R = \frac{L(Y_i, W_{\cdot i}, V_{\cdot i} | \theta_{s_i^*}^*)}{L(Y_i, W_{\cdot i}, V_{\cdot i} | \theta_{s_i}^*)} \text{ and}$$

$$L(Y_i, W_{\cdot i}, V_{\cdot i} | \theta_j^*) = L(Y_i | W_{li}, V_{li}, \beta_{0j}^*, \tau_{\epsilon}, \beta_l \forall l) \times \prod_{l=1}^{L} L(W_{li}, V_{li} | \theta_j^*)$$

When updating the configuration indicators  $s_i$ , there are two potential moves which would alter the number of distinct points in  $\theta^*$ . If  $n_{s_i}^{(-i)} = 0$  (i.e. the *i*<sup>th</sup> observation is currently a singleton), unless a proposal of  $s_i^* = K_{\theta} + 1$  is accepted, there is now one less distinct point in  $\theta^*$ . Therefore,  $K_{\theta} = K_{\theta} - 1$ . Similarly, if  $n_{s_i}^{(-i)} > 0$  and a proposal of  $s_i^* = K_{\theta} + 1$  is accepted, then  $K_{\theta} = K_{\theta} + 1$ .

**Step 1b:** After updating each  $s_i$ , let  $K_{\theta}$  denote the current atoms in  $\theta^*$  where  $n_j > 0$ . For j=1,2,..., $K_{\theta}$ , update  $\theta_j^*$ . This entails a series of independent updates for each element of  $\theta_j^*$ . Begin by sampling  $\beta_{0j}^*$  from a Normal  $(\mu^*, \tau^*)$  distribution, where

$$\tau^* = n_j \tau_{\epsilon} + \tau_0$$
  
$$\mu^* = \frac{1}{\tau^*} \left[ \tau_{\epsilon} \sum_{i:s_i=j} \left( Y_i - \sum_{l=1}^L X_{li} \beta_l \right) + \tau_0 \mu_0 \right]$$

Then, for l = 1, 2, ..., L, the unnormalized log full conditional density for  $\theta_{jl}^*$  takes the following form.

$$\log \left[\theta_{jl}^{*}|s, W, V\right] = \theta_{jl}^{*} \sum_{i:s_{i}=j} \left(2V_{li} + W_{li}\right) - 2n_{j} \log \left(1 + e^{\theta_{lj}^{*}}\right) - \frac{\tau_{\theta}}{2} \left(\theta_{lj}^{*} - \mu_{\theta}\right)^{2}$$

Although the above log target density does not take a standard distributional form, the density is log-concave, and so a new value for  $\theta_{jl}^*$  can be sampled using Adaptive-Rejection sampling (?).

#### **STEP 2:** Update for $\beta_l$

In order to update each  $\beta_l$ , we employed the Blocked Gibbs Sampler of ?. The Blocked Gibbs Sampler is based on the stick-breaking representation of the Dirichlet Process, discussed in the work of ?. Although the stick-breaking representation of the DP involves an infinite sum of discrete points, in actual implementation, the Blocked Gibbs Sampler utilizes a finite approximation, imposing a limit  $F_L$  to the number of distinct atoms amongst the  $\beta_l$ . Denote this collection of distinct points as  $\beta^* = [\beta_1^*, ..., \beta_{F_L}^*]$ . ? show that even for large sample sizes, a limit of  $F_L = 150$  provides a suitable approximation to the Dirichlet Process. Because of the point mass mixture construction in  $H_0$ , without a loss of generality, we can include the additional distinct point  $\beta_0^*$  to represent the cluster denoting no effect (i.e.  $\beta_{l1} = 0$  and  $\beta_{l2} = 0$ ) with associated model weight  $\pi$ . Similar to the configuration representation for  $\theta_i$ , define the pointers  $z_l$  where  $z_l = j$  if and only if  $\beta_l = \beta_j^*$  for  $j = 0, 1, 2, ..., F_L$ . Then define  $m_j$  as the number of  $z_l$  currently equal to j.

**Step 2a:** For  $j = 1, 2, ..., F_L$ ; update  $\beta_j^*$ . Note, because  $\beta_0^*$  represents the null effect cluster, its value need not be updated. If  $m_j = 0$ , then  $\beta_j^* \sim H_0$ . Else draw  $\beta_j^* \sim MVN_2(M^*, T^*)$  where

$$T^{*} = \tau_{\epsilon} G'_{j} G_{j} + T_{\beta}$$
  

$$M^{*} = (T^{*})^{-1} \left[ \tau_{\epsilon} G'_{j} \left( Y - B_{0} - X \beta^{(-j)} \right) + T_{\beta} M_{\beta} \right]$$

Y denotes a  $n \times 1$  column vector of the quantitative traits  $Y_i$ . Similarly,  $B_0$  represents a  $n \times 1$  column vector where the  $i^{th}$  element is  $\beta_{0s_i}$ .  $G_j$  is a  $n \times 2$  matrix whose  $i^{th}$  row equals  $\left[\sum_{l:z_l=j} W_{li} \sum_{l:z_l=j} V_{li}\right]$ . Finally,  $X\beta^{(-j)}$  is a  $n \times 1$  column vector whose  $i^{th}$  element is  $\sum_{c:z_c \neq l} X_{ci}\beta_{z_c}^*$ .

**Step 2b:** For l = 1, 2, ..., L; independently sample  $z_l$  where,

$$P(z_{l} = 0) \propto \pi L(Y|s, \beta_{0}^{*}, \tau_{\epsilon})$$

$$P(z_{l} = j) \propto (1 - \pi)p_{j}L(Y|s, \beta_{j}^{*}, \tau_{\epsilon}) \text{ for } j = 1, 2, ..., F_{L}$$
where
$$L(Y|s, \beta_{j}^{*}, \tau_{\epsilon}) \propto \exp\left[\frac{-\tau_{\epsilon}}{2}\sum_{i=1}^{N}\left(Y_{i} - \beta_{0s_{i}} - X_{li}\beta_{j}^{*} - \sum_{c \neq l}^{L}(X_{ci}\beta_{z_{c}})\right)^{2}\right]$$

**Step 2c:** Update  $\pi$  and the stick-breaking weights  $(p_j)$ . Sample  $\pi \sim \text{Beta}(c_1 + m_0, d_1 + (L - m_0))$ . Then for  $j = 1, 2, ..., F_L$ ; set

$$p_{1} = V_{1}$$

$$p_{k} = (1 - V_{1})(1 - V_{2}) \cdots (1 - V_{k-1})V_{k} \text{ for } k = 2, 3, ..., F_{L} - 1$$
where
$$\left(\alpha_{H} - \alpha_{H}(F_{L} - k) - \sum_{k=1}^{F_{L}}\right)$$

$$V_k \sim \text{Beta}\left(\frac{\alpha_H}{F_L} + m_k, \frac{\alpha_H(F_L - k)}{F_L} + \sum_{c=k+1}^{F_L} m_c\right) \text{ for } k = 1, 2, ..., F_L - 1$$

Then because the  $p_j$  must sum to 1,  $p_{F_L} = 1 - \sum_{j=1}^{F_L-1} p_j$ .

#### **STEP 3:** Updating the scalar mass parameters of the Dirichlet Process $(\alpha_G, \alpha_H)$

If  $\alpha_G$  and  $\alpha_H$  are given Gamma priors, then they can be updated using the following procedure described in ?. Assume there are  $K_G$  and  $K_H$  distinct atoms in the configuration representations for both G and H at the current MCMC iteration.

**STEP 3a:** Update for  $\alpha_G$ 

- 1. Sample  $x_G | \alpha_G \sim \text{Beta}(\alpha_G, N)$
- 2. Let  $\pi_G$  equal

$$\pi_G = \frac{\eta_2 + K_G - 1}{\eta_2 + K_G - 1 + N(\lambda_2 - \log(X_G))}$$

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3. Sample  $\alpha_G | x_G, K_G \sim$ 

 $\pi_G \text{ Gamma}(\eta_2 + K_G, \lambda_2 - \log(x_G)) + (1 - \pi_G) \text{ Gamma}(\eta_2 + K_G - 1, \lambda_2 - \log(x_G))$ 

**STEP 3b:** Update for  $\alpha_H$ 

- 1. Sample  $x_H | \alpha_H \sim \text{Beta}(\alpha_H, L)$
- 2. Let  $\pi_H$  equal

$$\pi_G = \frac{\eta_3 + K_H - 1}{\eta_3 + K_H - 1 + L(\lambda_3 - \log(X_H))}$$

3. Sample  $\alpha_G | x_G, K_G \sim$ 

$$\pi_H \text{ Gamma}(\eta_3 + K_H, \lambda_3 - \log(x_H)) + (1 - \pi_G) \text{ Gamma}(\eta_3 + K_H - 1, \lambda_3 - \log(x_H))$$

# **STEP 4:** Update error precision $\tau_{\epsilon}$

Sample  $\tau_{\epsilon} \sim \text{Gamma}(\alpha^*, \lambda^*)$  where

$$\alpha^{*} = \frac{N}{2} + \eta_{1}$$
  
$$\lambda^{*} = \lambda_{1} + \frac{1}{2} \sum_{i=1}^{N} \left( Y_{i} - \beta_{0s_{i}} - \sum_{l=1}^{L} X_{li} \beta_{z_{l}}^{*} \right)^{2}$$